

Manual for remote control with TeamViewer

1. System requirements:

- Client PC with working internet connection (e.g. Surfstick)
- Physical connection between client pc and SEW frequency inverter must be established (e.g. USB11A or Ethernet cable)
- SEW MotionStudio v.6 and all necessary plugins must be installed
- TeamViewerQS.exe

You can download the client software with the following link:
<https://get.teamviewer.com/en/experttuenkersqs>

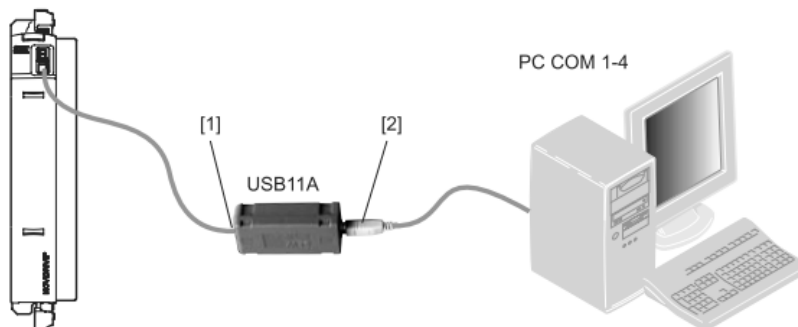
2. Physical connection between client pc and SEW inverter :

MOVIDRIVE[®]

Connection with Interface USB11A

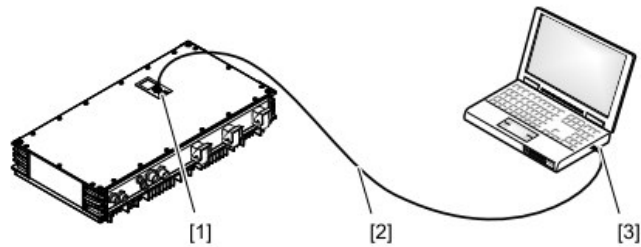
- To connect the USB11A with the MOVIDRIVE[®] use the cable connection [1] (RJ10 - RJ10)
- Connect the cable [1] with the XT slot of the MOVIDRIVE[®] and the RS485 slot of the USB11A
- Use the USB cable to connect the USB11A with the PC [2] (Type USB A-B)

MOVIDRIVE[®] MDX60/61B



MOVIPRO[®]

The following picture shows the connection between PC and engineering interface of the MOVIPRO[®]



[1] Service-Schnittstelle (Ethernet RJ45)
des MOVIPRO[®]

[2] handelsübliches Ethernet-Kabel
[3] Ethernet-Schnittstelle des Laptops



open



Insert
Ethernet cable

The default IP-address of the Ethernet engineering interface is:

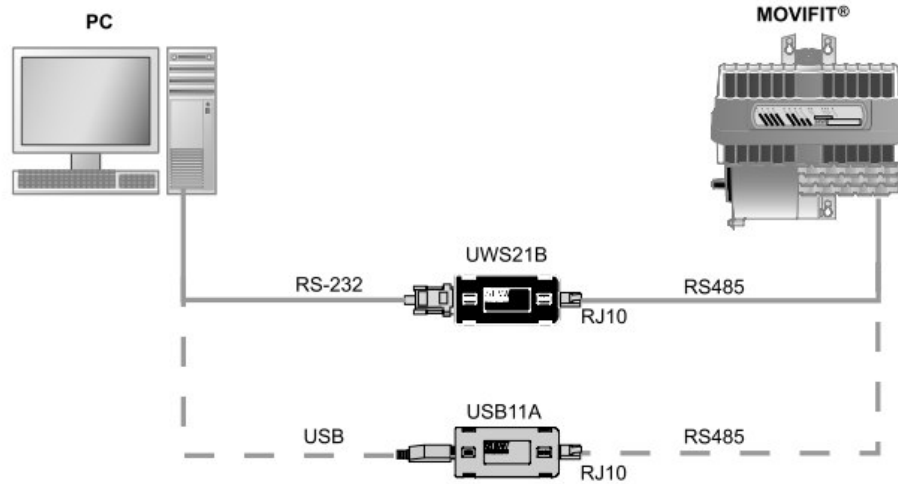
192.168.10.4

Subnet mask:

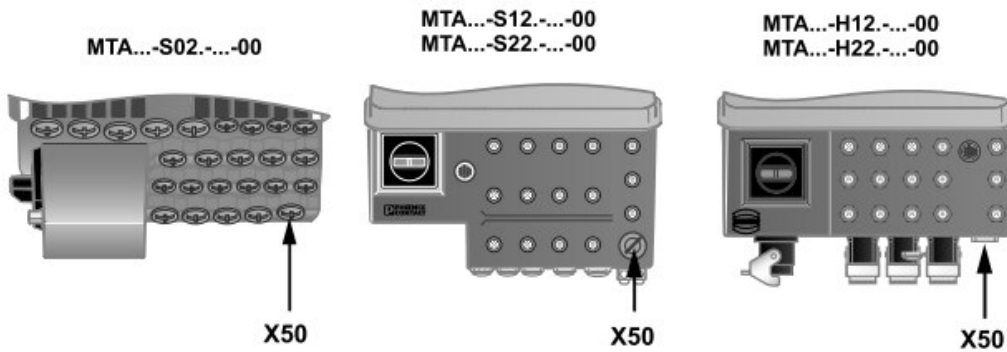
255.255.255.0

Assign an IP address to the client PC e.g. 192.168.10.1 / 255.255.255.0

MOVIFIT®



The connection with the MOVIFIT® is done via the diagnostic socket X50. The location of the diagnostic socket X50 is shown in the following picture. You have to remove the cable fitting.



Insert
RJ-10 cable

3. TeamViewerQS:

- Double click , TeamViewerQS dials up a connection to the Server.



- You have to deliver your ID and password to the service technician of EXPERT-TÜNKERS GmbH. For every session a new password has to be provided.